Optimizing Quantum Social Welfare in Non-collaborative Games

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Summary

- Non-collaborative games involving multiple players exhibit equilibria wherein no player has an incentive to deviate from their strategy
- The quality of an equilibrium can be quantified by its social welfare the mean payout each player receives
- Access to shared quantum resources may allow better cooperation, and hence better equilibria
- We consider two scenarios: in one, players may make measurements directly on a quantum state, while in the other, they delegate the measurement to a referee
- We study how to optimise the social welfare in these two settings and compare the classes of equilibria obtainable on several games as a function of the bias of the game

Non-collaborative games

Two types of quantum strategies

Question: How can quantum resources lead to new equilibria or improve social welfare?

We identify two types of quantum strategy and equilibria:

Quantum correlated strategies: Advice C is obtained from measurements on a quantum system:

$$C(s|r) = \operatorname{Tr}\left[\rho(M_{s_1|r_1}^{(1)} \otimes \cdots \otimes M_{s_n|r_n}^{(n)})\right]$$

- Measurement delegated to mediator, or performed by parties with quantum "black-boxes"
- **Quantum strategies** [2]: Each player measures a shared quantum state to determine their output a_i
 - Direct access to quantum resource
 - Notion of equilibria modified: a player can deviate by choosing any other local POVM: $\forall i \forall t_i \forall N^{(i)} = \{N_{a_i|r_i}^{(i)}\}_{r_i}$

A non-collaborative game G between n players is defined by:

• A set of **questions** $T \subseteq \{0, 1\}^n$

- A prior distribution Π over the questions T
- A set of valid answers $A \subseteq \{0, 1\}^n$
- A payout function u_i for each player *i*, with $u_i(a, t) \in \mathbb{R}$.
 - We consider payout functions with the form

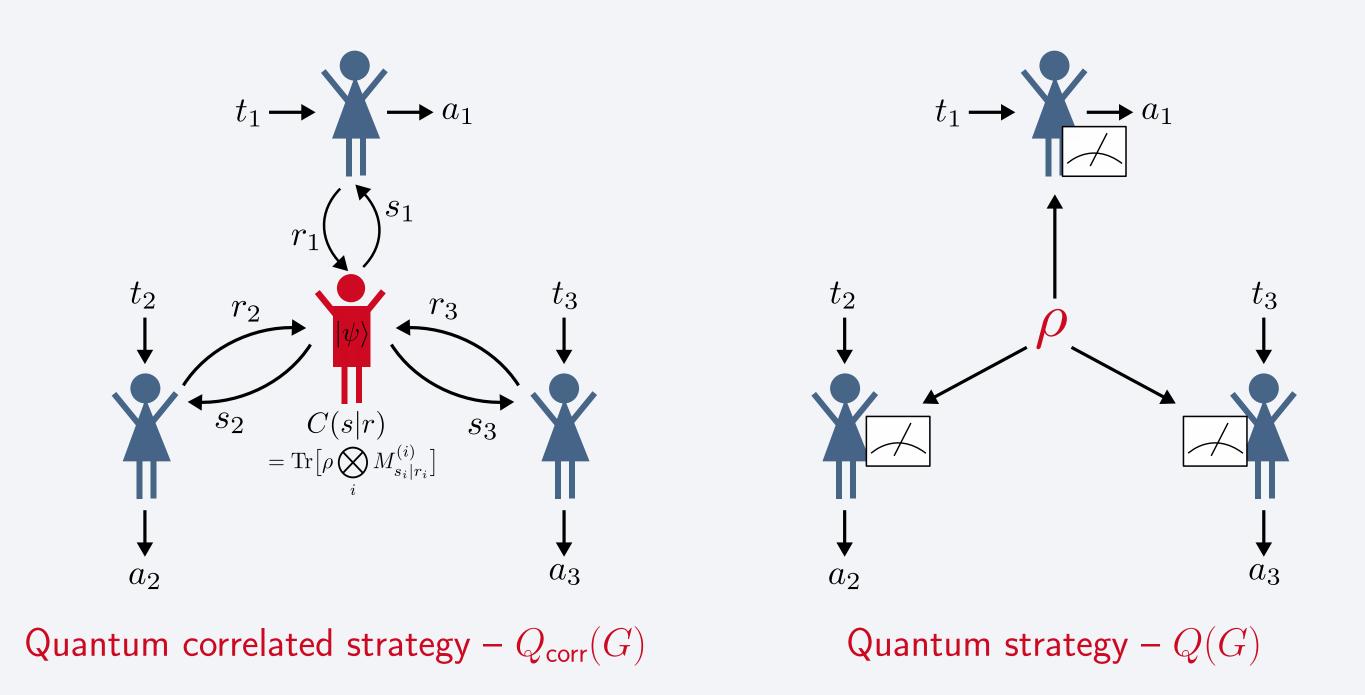
 $u_i(a,t) = \begin{cases} 0 \text{ if } (a,t) \in \mathcal{L} \\ v_0 \text{ if } a_i = 0 \text{ and } (a,t) \notin \mathcal{L} \\ v_1 \text{ if } a_i = 1 \text{ and } (a,t) \notin \mathcal{L}, \end{cases}$

- with $v_0, v_1 > 0$ and $\mathcal{L} \subseteq A \times T$ a set of "losing input-output pairs"
- Ratio v_0/v_1 controls the bias of game

Example: Winning conditions for two 5-player games: $NC_{00}(C_5)$ and $NC_{01}(C_5)$ [1]

${\displaystyle \underset{t_{1}t_{1}t_{2}t_{3}t_{5}}{{\sf Question}}}$	Winning condition, $NC_{00}(C_5)$	$Question_{t_1t_1t_2t_3t_5}$	Winning condition, $NC_{01}(C_5)$
10000	$a_4 \oplus a_0 \oplus a_1 = 0$	10100	$a_4 \oplus a_0 \oplus a_1 = 0$
01000	$a_0 \oplus a_1 \oplus a_2 = 0$	01010	$a_0 \oplus a_1 \oplus a_2 = 0$
00100	$a_1 \oplus a_2 \oplus a_3 = 0$	00101	$a_1 \oplus a_2 \oplus a_3 = 0$
00010	$a_2 \oplus a_3 \oplus a_4 = 0$	10010	$a_2 \oplus a_3 \oplus a_4 = 0$
00001	$a_3 \oplus a_4 \oplus a_0 = 0$	01001	$a_3 \oplus a_4 \oplus a_0 = 0$
11111	$a_0\oplus a_1\oplus a_2\oplus a_3\oplus a_4=1$	11111	$a_0\oplus a_1\oplus a_2\oplus a_3\oplus a_4=1$

 $\sum_{t_{-i},a} u_i(a,t) \operatorname{Tr}\left(\rho \cdot \bigotimes_j M_{a_j|t_j}^{(j)}\right) \Pi(t) \ge \sum_{t_{-i},a} u_i(a,t) \operatorname{Tr}\left(\rho \cdot \bigotimes_{j\neq i} M_{a_j|t_j}^{(j)} \otimes N_{a_i|t_i}^{(i)}\right) \Pi(t)$



For any game G, the sets of equilibria satisfy

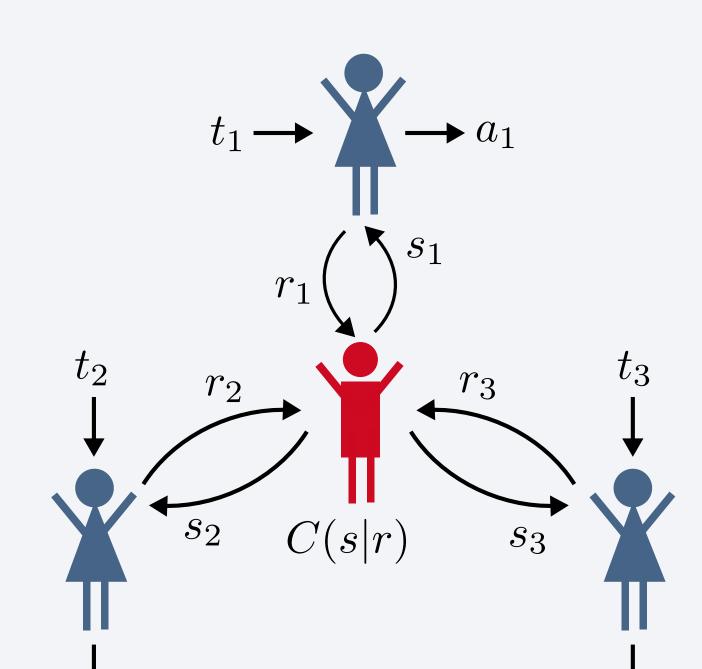
 $Nash(G) \subset conv(Nash(G)) \subset Corr(G) \subset Q(G) \subset Q_{corr}(G) \subset B.I.(G) \subset Comm(G)$

Results: Social welfare of different strategies

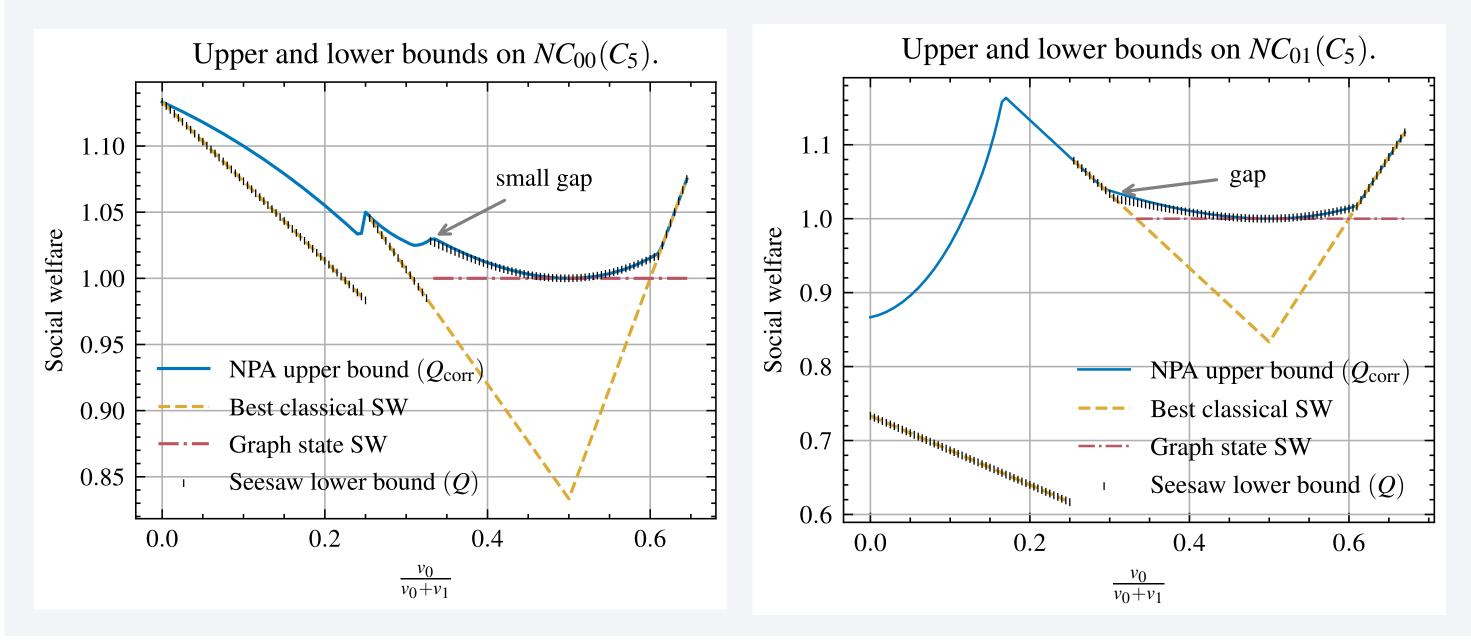
- Each player follows a local strategy to produce their answer
- In general, they may also have access to a shared correlation in the form of an advice s_i provided by a mediator with probability $C(s_1 \dots s_n | r_1 \dots r_n)$
- A solution (set of strategies for each player, defined by functions f_i and g_i) induces a distribution

 $P(a|t) = \sum_{\lambda} \Lambda(\lambda) \sum_{s: \forall i, g_i(t_i, s_i, \lambda_i) = a_i} C(s_1 \dots s_n | f(t_1, \lambda_1) \dots f(t_n, \lambda_n))$

• We can generally consider just deterministic strategies



- We optimised the social welfare over different strategy classes for three games: $NC_{00}(C_5)$, $NC_{01}(C_5)$, and $NC(C_3)$ (not shown here) [1]
 - Best classical SW: computed exactly
 - **Graph state SW:** pseudo-telepathic equilibria using GHZ states [1]
 - Seesaw lower bound: numerical optimisation by iterating SDPs to find explicit strategies lower-bounding QSW over Q(G)
 - **NPA upper bound:** SDP hierarchy providing dimension-independent upper bound on equilibria in $Q_{corr}(G)$ [3, 4]



Conclusions and open questions

- Two different ways to use quantum resources lead to distinct classes of equilibria
- A solution is a Nash equilibrium if no player can increase their mean payout by changing their strategy: $\forall i \forall t_i, r_i \in T_i \forall \mu_i : T_i \times A_i \to A_i$,

$\sum_{t_{-i},a_{-i}} u_i(a,t) P(a|t) \Pi(t) \ge \sum_{t_{-i},a_{-i}} u_i(\mu_i(t_i,a_i)a_{-i},t) P(a|r_i t_{-i}) \Pi(t)$

- Nash equilibria play important roles in applications from economics to engineering
- Different correlations C lead to different equilibria: Nash (no correlation), Corr (shared randomness), B.I. (belief invariant, or no-signalling),
- The **social welfare** of a solution is

 a_2

$$SW(P) = \sum_{a,t} U(a,t)P(a|t)\Pi(t), \text{ where } U(a,t) = \frac{1}{n}\sum_{i} u_i(a,t) = \frac{1}{n}\sum_{i} u_i(a,t)$$

- Numerical evidence of strict separation between Q(G) and $Q_{corr}(G)$, but analytic proof still to be found
- Quantum social welfare can be improved beyond pseudo-telepathic strategies
- Methods to directly obtain upper bounds on Q(G) and lower bounds on $Q_{corr}(G)$?

References and acknowledgments

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